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LED SOURCES - RELEVANCE FOR VISUAL SIGNAL DETECTION



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Short Profile

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ABSTRACT:

Visual signalling devices using lightemitting diodes (LEDs) are increasing in number. LEDsources have a number of characteristics that are particularly well suited for signal applications: very rapid onset and offset times, straightforward temporal control of luminous intensity throughadjustment of current or voltage properties, saturated colour that provides relatively high perceived brightness, and robust performance resulting in long useful lives, with appropriate hermal design. With specific emphasis on the capabilities and unique properties of LED lightsources, the relevance of humanfactors research findings from various signal lightingapplications to visual warnings and alerts for fire and emergency protection are discussed,

including environments where visual effectiveness can be reduced, such as in smoke or fog. Some preliminary guiding principles regarding the visual effectiveness of signal and warningdevices for fire protection using LEDs are also summarized. Considerations and criteria foreffectiveness will include ensuring detection, minimizing response times, providing an ability tolocate a warning signal or device, and helping ensure that the warning or signal can be identified and interpreted properly.

KEYWORDS

Light-emitting diodes (LEDs), Visual Signals, Perception, Colour Identification.

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INTRODUCTION

Light-emitting diodes (LEDs) are growing in use for a number of visual signalling applications, including vehicle signals (Bullough et al. 2001, 2007a), road traffic signals (Bullough et al., 2000, 2005), aviation signal lights (Bullough et al. 2007b; Radetsky et al. 2009; Skinner and Bullough 2011; Skinner and Greenfield 2011), and work zone lighting (Bullough et al. 2011a). They are also being considered for visual signaling applications in fire and emergency alarm systems in building interiors. In this paper, the characteristics of LEDs and potential implications for various visual responses are briefly described.

LED TECHNOLOGICAL CHARACTERISTICS

LED sources have undergone rapid increases in luminous efficiency (lm/W) and in light output in recent decades, making them viable alternatives for such applications. Table 1 summarizes the photometric, colorimetric and temporal characteristics of LEDs along with those of other sources that might be used in some visual signalling applications.

It can be seen from Table 1 that tungsten filament lamps such as incandescent have relatively low luminous efficacies. The relatively large source size of fluorescent and compact fluorescent lamps, and their relatively long "warm-up" times can make them less suitable for many signalling applications. Issues with long warm-up and re-strike times of metal halide lamps are complicated even further. Xenon strobe lamps are the most common sources for fire alarm visual signals, but the high efficiency, rapid onset time and long operating life of LED sources are making them attractive alternatives to consider for this application.

Light Source	Efficiency	Life (hours)*	Correlated	Onset
	(lm/W)		ColourTemperature	Time†
			(K)	
Tungsten filament lamp	12-20	750-4000	2700-3200	0.1-0.3 s
Fluorescent	60-100	10,000-30,000	2700-7500	1-60 s
Metal halide	80-110	10,000-20,000	2800-5000	60 300 s
Xenon	30-60	1000-5000	5000-6999	1 µs
LED (white)	90-130	50,000-100,000	3000-8000	10-20 ns

Table 1.Light Source Characteristics

*Assuming steady operation.

⁺Time to reach 90% of maximum light output.

In addition to the characteristics listed in Table 1, the light output of LED sources can be manipulated in a fairly straightforward manner through changing the current through the LEDs, or using pulse-width modulation (PWM) where the LED is modulated at a very high frequency above the critical fusion frequency of around 100 Hz (De Lange 1958; Kelly 1961; Bullough et al. 2011b), and the duty cycle is adjusted so that the apparent output is linearly correlated with the duty cycle.

VISUAL RESPONSES TO LED SIGNAL LIGHTS

As described above, LEDs have been used in a wide range of visual signalling applications and there is a substantial body of research relating the characteristics of LED signal lights to various visual responses, each with varying degrees of relevance to visual signals for fire alarm systems.

RAPID SIGNAL DETECTION

A key visual response for nearly any signal light is the ability to detect it with sufficiently high probability and with a reasonably short reaction time. Bullough et al. (2000) measured the reaction times of individuals to the onset of simulated road traffic signals viewed against a bright background such as the daytime sky. The signal sizes were such that they subtended the same visual angle as a 200-mm-diameter traffic signal viewed from a distance of 100 m. For each of the three road traffic signal colours (red, yellow and green), the reaction times, when plotted as a function of the luminous intensity of the signal, followed a power function where reaction times decreased sharply as a function of increasing intensity at low intensity values, but levelled off to asymptotic values at higher intensities.

There were also differences among the colours. Reaction times to the red signal lights were shorter than to yellow and green signals of the same luminous intensity under simulated daytime conditions with bright backgrounds. In comparison, at much lower background light levels, Ueno et al. (1985) found little difference among colours. Because the red signal colour used by Bullough et al. (2000) was highly saturated in appearance relative to the yellow and green signals, the increased chromatic information may have helped in providing more rapid detection when the relative intensity difference between the signal light and its background was smaller, such as during daytime viewing conditions. For darker background conditions, where the intensity difference between the signal light and its background is much larger, light level is high, as during daytime in spaces illuminated in part by daylightthe ability to detect the signal rapidly appears to depend mainly on its luminous intensity regardless of colour. White signal lights are not saturated in terms of colour, so it might be expected that reaction times to the onset of white flashing lights would be longer than for signal lights of equal intensity but collared appearance when the background.

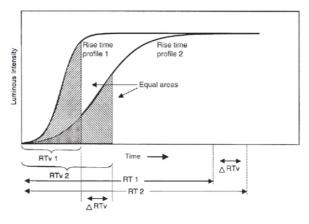


Figure 1.Illustration of the light energy threshold concept, plus a fixed nonvisual response time, used to predict reaction times to the onset of a signal light (Bullough2005).

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BASE	EBSCO	Open J-Gate

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The onset time characteristics of LEDs, as illustrated in Table 1, are nearly instantaneous with rise times of 10-20 ns (1 ns = 10_{-9} s). In comparison, tungsten filament sources can take up to 300ms to achieve nearly-full light output because of the thermal mass of the incandescent filament as it is heated to produce light. Bullough (2005) reported the results of an experiment to measure reaction times to the onset of yellow and red signal lights with different rise times, ranging from about 20 to 200 ms. Interestingly, reaction times were predicted by a fixed light energy threshold (in cd•s) that depended upon the colour, but not the onset time. Once the necessary light energy threshold (9 cd•s for yellow lights and 5 cd•s for red lights) was produced, a fixed nonvisual reaction time of 367 ms was added to the time needed to achieve the threshold light energy, to account for the physical motor movements involved in pressing a switch to indicate that the light was detected. For white light, the threshold light energy would be expected to be closer to that of yellow signal lights than for red, because of the lower saturation of white and yellow light compared to red light. Although the reaction times to signal lights with shorter onset times were systematically shorter, the probability of detecting the signal light within 1 s was not affected by the onset time.

BRIGHTNESS PERCEPTION

Fire alarm signal lights use white light to produce the necessary visual signal. If two lights have different correlated colour temperatures (CCT), they can be judged to have different perceived brightness even if their luminous intensities (in cd) are identical. Ware and Cowan (1983), integrating the results from a large number of experiments, found that the perceived brightness of a saturated patch of light, or of a patch of light with a higher CCT, could be quantified in terms of the brightness/luminance (B/L) ratio relative to a standard white patch of light, such as from an incandescent source. A collared patch of light with a B/L value of 2.0 would need only 50% the luminance (1/2.0) to be judged equally bright as the standard patch of light.

Because the B/L values from Ware and Cowan (1983) were based on patches of light, and not on points of light such as those seen when a signal light is viewed, Bullough et al. (2007b) compared the brightness/luminous intensity (B/L) values of point sources viewed under different conditions, including white signal lights varying in CCT. They found that a signal light with a higher CCT than incandescent (which is represented in Figure 2 by the white chromaticity region labelled 1.0) could have B/L values of 1.2 to 1.6, depending upon the CCT.To the extent that signal lights that appear brighter may be judged as more conspicuous, light sources with higher CCTs might increase the quality of white signal lights.For collared signal lights, perception of brightness seems to be related to the saturation of colour. In Figure 2, blue and green signal lights 5 with the highest B/L values are those located closest to the spectrum locus, with the greatest saturation.

LED SOURCES - RELEVANCE FOR VISUAL SIGNAL DETECTION

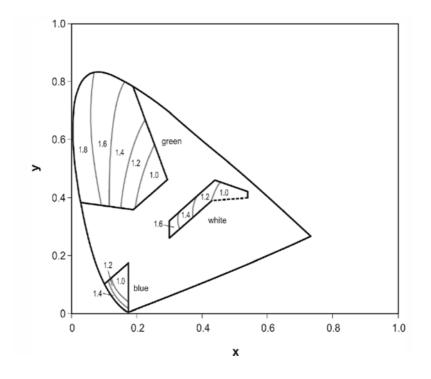


Figure 2.Measured B/L values for white, green and blue signal lights having different chromaticities (Bullough et al. 2007).

COLOUR IDENTIFICATION

Visual signals for fire alarm systems are supposed to be white; therefore, the ability to correctlyidentify the colour may not be as directly relevant to such systems as for the correct identification of signal lights for roadway traffic control or for aviation signalling along airport runways andtaxiways. However, it has been demonstrated that for relatively low CCT white light sources, such as incandescent lamps using tungsten filaments, these nominally white light sources cansometimes be identified as yellow (Bierman et al. 2009; Skinner and Bullough 2011). In contrast, when the CCT is higher, such as above 4000 K, the likelihood of an incorrect identification is much lower.

Skinner and Bullough (2011) also reported colour identification data for both colour-normal and colour-deficient observers to incandescent (filtered) and LED signal lights varying in colour (red, yellow, green, red and blue), and found that for both colour-normal and colour-deficient observers, the increased saturation generally resulted in improved colour identification.

DISTANCE/LOCATION JUDGMENT

Some signal lights are meant simply to provide notification or detection (such as visual signals for fire alarm systems), whereas others may also require individuals to identify where the signal light is. For example, being aware that a vehicle's brake lights have been activated is an important visual response while driving, but it is also necessary to know from which vehicle the signal was produced, so that appropriate steering or braking manoeuvres can be made. Such judgments can be more difficult

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when smoke, fog or snow is present because these materials scatter light throughout the field of view, and can obscure the location of a source of light.

With respect to flashing lights, Bullough et al. (2001) measured drivers' ability to detect when as now break truck, being driven ahead of the driver's vehicle during snowy weather, was beginning to slow down. Two rear lighting configurations on the snow plow truck were used: one was a pair of flashing lights, and the other was a pair of steady-burning lights mounted along the sides of the rear of the truck. In both conditions, the truck was also equipped with a rotating beacon light on the roof of the cab. Subjects in this study were able to detect the snow plow's deceleration sooner with the steady-burning lights than with the flashing lights. This is consistent with previous studies of people's ability to catch a thrown object under steady versus illumination (Croft 1971), and of driver's recognition of flashing warning lights along highwaywork zones (Bullough et al. 2011). Tracking a moving object is more difficult when the visual information provided is intermittent.

CONCLUSION

It is clear that LED light sources have strong promise for a number of visual signalling applications. Their shortonset times, range of available CCTs, long rated lives, and increasing luminous efficacy make them attractive for visual signalling. Of course, visual signalling for fire alarm systems has different requirements than for other signalling applications such as those for transportation, but the research literature on LED signal lights for transportation can lead to several guiding principles for optimizing visual responses.

• Response times to signals with short onset times (such as LEDs) are shorter than to those with longer onset times. Driving circuitry for LED signal lights should avoid using electrical components that will result in long (>10-20 ms) onset times in order to minimize visual reaction times.

• If LEDs will be used to produce multiple-pulse flashes of light, minimizing the duration between pulses will result in higher effective intensity values more likely to be judged as more conspicuous.

• If a flashing signal light is to be both detected and localized in the field of view, maintaining a steadyburning component will help people identify the location and distance of the light from the viewing location, especially in smoke or other perturbed atmospheres.

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LED SOURCES - RELEVANCE FOR VISUAL SIGNAL DETECTION

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